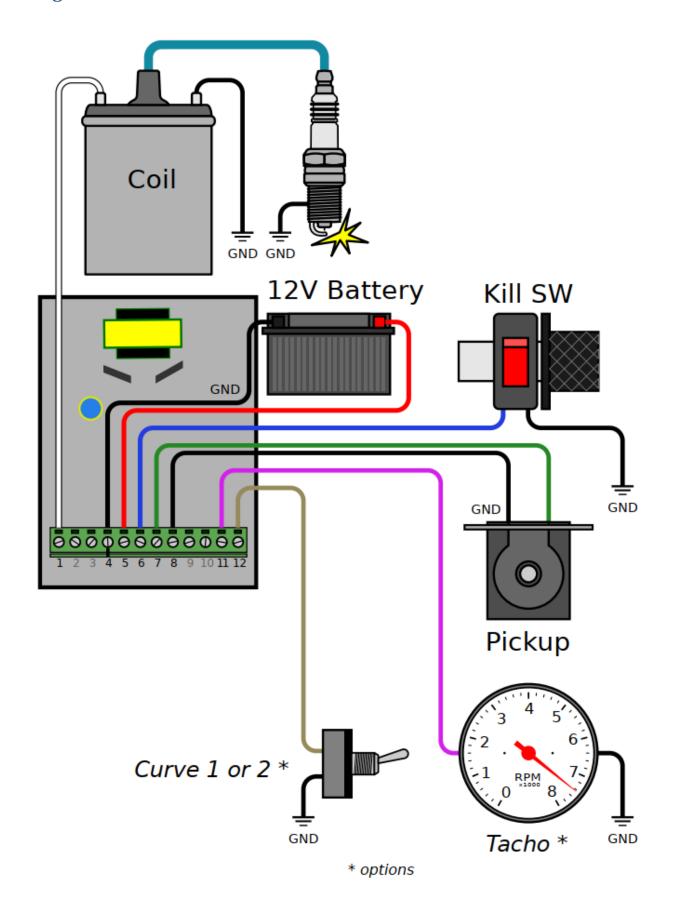
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Wiring



Connector



1	output	To ignition coil	
2	output	To ignition coil	(pin1 and 2 are connected together)
3	output	not connected	(Test Point to measure HighVoltage)
4	input	Ground frame (=mi	nus from battery)
5	input	+12Vdc from batte	ery
6	input	Kill switch	
7	input	Analog Pickup	
8	input	Pickup or Hall Sensor Gro	ound
9	input	Digital Hall Effect Sensor	
10	input	not connected	(Except for XT600: Pickup at 12°)
11	output	Tachometer *	
12	input	Curve Selection *	

Kill Switch

The ignition uses the Kill switch input as a selector between <u>2 functions</u>:

- <u>Setup</u>
- Stop engine.

Setup Mode

- 1) Turn the Kill Switch ON (connector pin6 connected to ground) PRIOR to power on the ignition box.
- 2) **Power on** the ignition box with a 6 to 12v battery.

Warning: The Power and Ground connections MUST BE SECURE.

A power outage during the setup process may cause the ignition box to brick!

When the ignition box detects that the kill switch is already grounded, it turns into SETUP Mode.

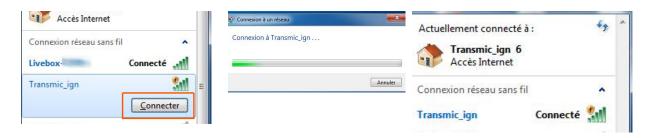
3) The **Led** <u>blinks 5 times</u> meaning grounded Kill switch has been detected.

Then wait for the WiFi server to start,
then blinks 5 times again meaning "Wifi Ready" and finally flashes once every 5 seconds.

- 4) The ignition box starts a Wifi AP (Access Point)
- 5) On your phone, laptop, PC, whatever, go to the Wifi setting and search for a new SSID called Transmic_ign



6) Connect to it. Password is required: it's "password"



- 8) Once your device is connected to the AP, open up a **browser** and head over to http://192.168.4.1/setup (http not https!)
- 9) Once connected your browser should display:

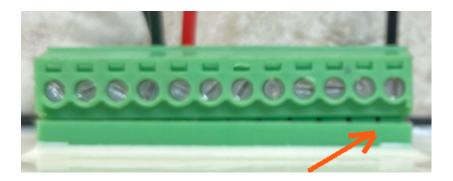
TRANSMIC.FR

<mode>
<

10) Turn the Kill Switch OFF for Running mode.

Troubleshooting WiFi connection

- Check that the 12pins connector is FULLY inserted and there is nothing preventing the male connector from fully engaging.



- Reboot the ignition box. (Power off/power up)
- Ignore any browser message saying it's not connected to internet. It's not an Error, it's a Warning:

ie: Firefox on W10:



Iphone11:

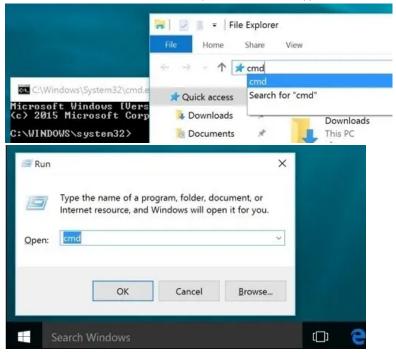


Indeed, **it's connected ONLY to the Ignition box**, **not to the web.** (*It's impossible to reach Google and the ignition box at the same time*)

- You can see available SSID with a WiFi Monitor as Wifi Analyzer for Android or Wifi-Analyzer for W10
- You can test the network connection from your laptop to the ignition box:

Open a command Prompt:

Type "cmd" into the address bar of File Explorer and hit Enter or Press Windows+R to open "Run" box. Type "cmd" and then click "OK"



ping the ignition box, it should replies:

C:\>ping 192.168.4.1

Pinging 192.168.4.1 with 32 bytes of data:

Reply from 192.168.1.1 : bytes=32 time<1ms TTL=64 **Reply** from 192.168.1.1 : bytes=32 time<1ms TTL=64 **Reply** from 192.168.1.1 : bytes=32 time<1ms TTL=64

Clear DNS cache

Windows: in MsDos console: C:\>ipconfig /flushdns

MacOS: in Terminal : sudo dscacheutil -flushcache

Linux: in Terminal: sudo systemd-resolve –flush-caches

Troubleshooting display

Console URL is http:// NOT https:// but some browsers like Chrome automatically switch to secure https://

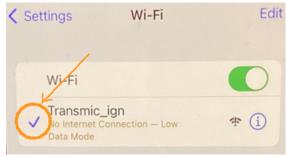
- Or use Firefox. *Close <u>all</u> Firefox windows than relaunch it.*
- Or use a lightweight, portable browser as **QtWeb**
- or <u>disable **HSTS**</u> In Chrome.

iPhone won't connect to Wifi AP

You may be not prompted for a password.

Apple devices try "weak" passwords in the background!

If the Iphone is connected to SSID "Transmic_ign" (Check mark below) that means it guessed the right pwd.



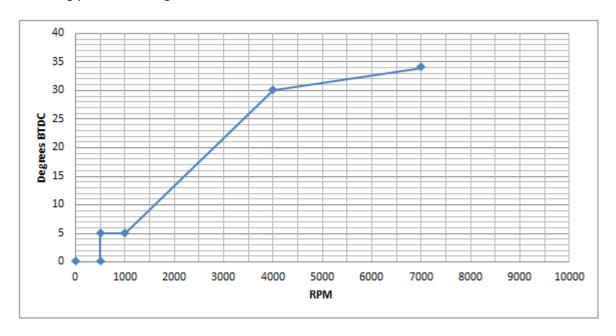
- 1) Disconnect Cellular data
- 2) Forget the "transmic_ign" SSID and connect to it again: https://youtu.be/yQKFOLIKIqo?si=A0CFfJYSo3uqEjml&t=18
- 3) Remove interworking from the wifi configuration: Settings > Cellular Data > Wi--Fi Calling: Off
- 4) Disable the automatic switch to mobile data when Wi-Fi connectivity is "poor" Settings > Mobile Service > Wi-Fi Assist: off https://youtu.be/yQKFOLIKIqo?si=AaP1W3ZmdztTiKkh&t=162
- 5) Disable WiFi Auto-join to your local network: https://youtu.be/9vM95hlBW-c?si=xnFNmgoxQUGXkSbJ&t=18

Check your WLAN settings under:

Settings > Maintenance > Support Info > System Config > Show System Config

Ignition Timing

Assuming you want this ignition curve:



One can define the curve with 4 points but you can use up to 13 points.

(0 to 500rpm at 0° BTDC is <u>hard coded</u> for no kickback.)

The curve above is defined by 4 pairs of values

```
500 rpm = 5° BTDC
1000 rpm = 5° BTDC
4000 rpm = 30° BTDC
7000 rpm = 34° BTDC
```

Those 4 couples of values MUST be filled out in the form <u>consecutively and in ascending order</u> of RPM along with the pickup position.

Use this Windows software to draw the curve: Interactive_Graph.exe with Video

Pickup Type

Default: 0

MENU	PICKUP TYPE	PICKUP POSITION
STROKES	SHAFT	CYLINDERS
ADVANCE TIMING	ADVANCE 0-500rpm	AUTO SPARK
DWELL	BYPASS	CONSOLE
MODIFY	UPDATE	

[0]

- 0: Analog Pickup Coil (VR-PN)
- 1: Analog Pickup Coil (VR-NP)
- O 2: Digital Hall Effect Sensor *

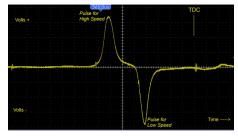
Send

* option

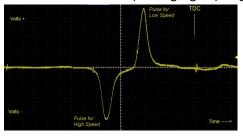
Select the type of pickup attached to the Ignition box:

When the LEADING edge of the magnet passes in front of the pickup coil, a wave is produced and another wave of opposite voltage is generated when the FALLING edge of the magnet leaves the pickup coil. Depending on the wiring, the first pulse at Leading Edge can be positive (then negative at Falling edge), or the exact opposite.

0 = VR stands for Variable Reluctor aka pickup coil/trigger coil (Analog signal) Positive first (PN)



1 = Variable Reluctor (Analog signal) Negative first (NP)



2 = Hall Effect Sensor (Digital signal)

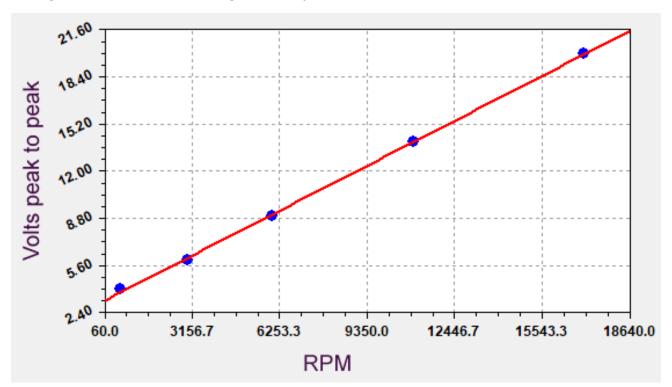
This ignition box works best with Positive first pickup (VR-PN)

If the pickup is internally grounded into the stator there is no choice, the pickup output is either PN or NP But if both pickup wires are available, then just swap the wires to change the polarity in order to get a **Positive first** signal (PN) on connector **pin7**.

Pickup voltage

In order to be detected by the ignition, the VR pickup MUST deliver sufficient voltage.

The higher the RPM, the more voltage it should produce.



Formula:

Minimum Vpp voltage to be detected = RPM/1000 + 3

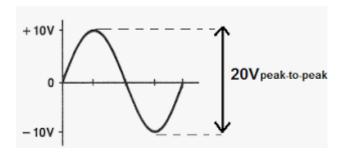
Example:

At **6000rpm** the VR pickup must put out:

6000/1000 = 6

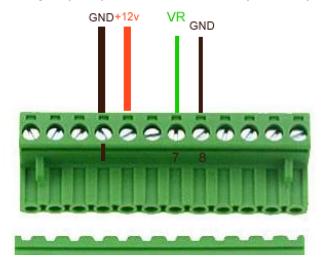
6 + 3 = 9Vpp

9Vpp = +4.5v to -4.5v



VR pickup

Analog VR pickup is connected between pin 7 and pin 8/gnd

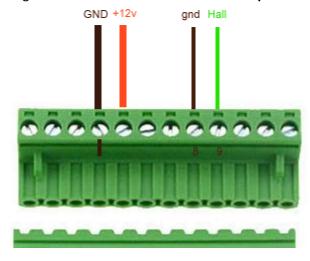


To avoid ElectroMagnetic Interference (EMI) it's safer to connect the pickup sensor through a shielded cable. Shield grounded on one side only.

Twisted pair is better.

Hall Sensor

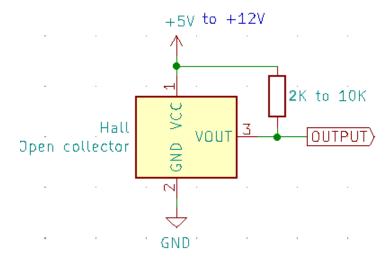
Digital Hall Sensor is connected between pin 9 and pin 8/gnd



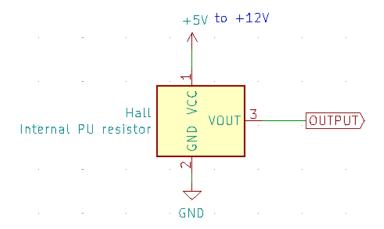
<u>Pickup Type</u> must be set to [2] for use of a Hall sensor.

2 types of Sensors

- Hall sensors with **open-collector** output, give a floating voltage when no magnet. They needs a pull-up resistor.



- Hall sensors with **built-in pull-up resistor** give positives voltage when no magnet.

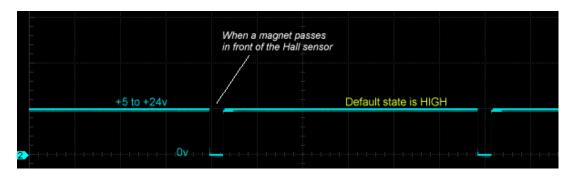


Hall sensors require a +5v to +12vdc supply voltage. See datasheet

You can even connect an **Optical Sensor** as long as it puts out a CLEAN square signal similar to the one above.

See Appendix 2 for Position

Output of a Hall sensor



Timing

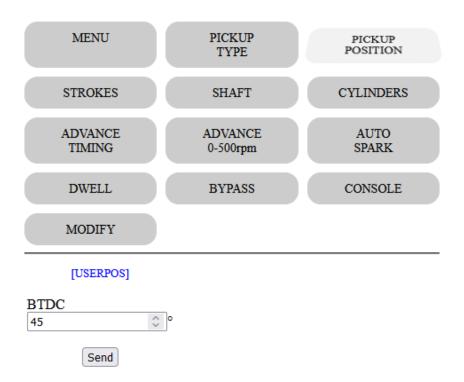
The ignition box uses the **rising edge** of the Hall sensor signal.



Pickup Position

Default: 50

Range of values: 1 to 180



- Go back to the opened browser and first thing first, enter the Pickup Position then click Send

Formula is: *Pickup position = Base advance + Magnet Length*





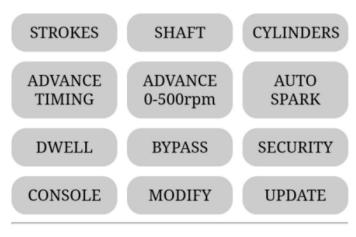
Base advance is generally 5 to 15° BTDC

See Appendix 1,2,3,4 to find the physical position of the pickup relative to TDC.

Current value appears in blue on the form.

Strokes

Default: 2



[2]

- 2 strokes
- 04 strokes with Wasted Spark
- ○4 strokes No Wasted Spark

Send

2 strokes : One pickup pulse every rotation

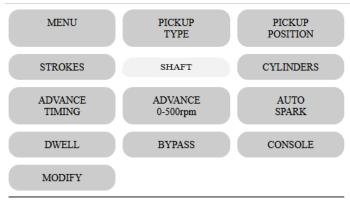
4 strokes with Wasted Spark: One pickup pulse every rotation = spark at TDC + wasted spark at BDC

4 strokes No Wasted Spark: One pickup pulse every 2 rotations = spark at TDC only

4 strokes with Wasted Spark is the most common case.

Shaft

Default: 0



[USERSFT]

- 0: CrankShaft
- O1: CamShaft
- O 2: 2pulses/rev

Send

- Select if the pickup is placed:
 - 0: on the crankshaft via the flywheel (2stk) with 1 pulse per rotation
 - **0**: on the **crankshaft** via the flywheel (4stk) with 1 pulse per rotation with wasted spark. (one spark occurs during the compression stroke and another during the exhaust stroke.)
 - 1: on the camshaft (4stk) with 1 pulse per 2 rotations.
 - 2: on the crankshaft with 2 pulses per rotation

Current value appears in blue on the form.

Advance Timing

- Proceed now to enter the advance timing.

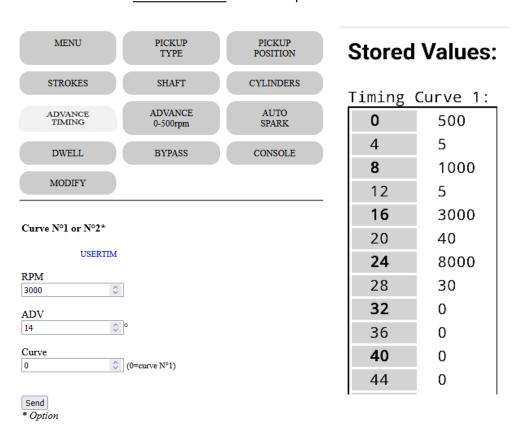
We want to setup:

```
500 \text{ rpm} = 5^{\circ} \text{ BTDC}
1000 \text{ rpm} = 5^{\circ} \text{ BTDC}
4000 \text{ rpm} = 30^{\circ} \text{ BTDC}
7000 \text{ rpm} = 34^{\circ} \text{ BTDC}
```

Enter values consecutively in ascending order of RPM!

Pair 500:5 first etc etc...

7000 being the <u>last value</u> (as the firmware stops reading when it meets a null value), 7000 will act as the <u>hard rev-limiter</u>: No more sparks at 7001 RPM!



RPM can be entered with a 100rpm step but RPM will be measured with **1rpm** precision.

Timing can be entered with a precision of 1° but the processor calculate all timing values between the points you entered, using linear interpolation so an **accuracy of 0.1°** is done at this step.

Any timing values will be COMPLETELY OFF IF PICKUP POSITION IS FALSE: PICKUP POSITION IS KEY

See Appendix 1 for Position

Curve N°1 is stored at addresses 0 to 100

Select curve

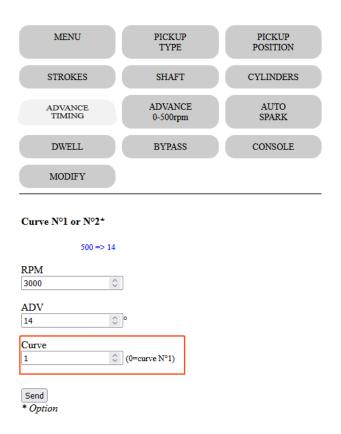
Default: curve N°1

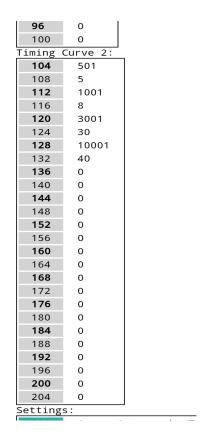
If you bought the 2 curves option, then connect a switch between connector pin 12 and ground.

When switch is **open** (or no switch connected), **curve N°1** is used.

If switch is **on** (pin 12 connected to ground) BEFORE turning on the ignition box, then **curve N°2** will be used.

You cannot change the curve while running. (The switch is not read by the ignition)

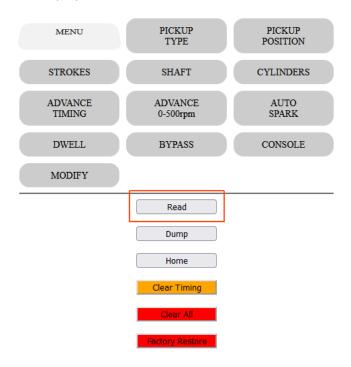


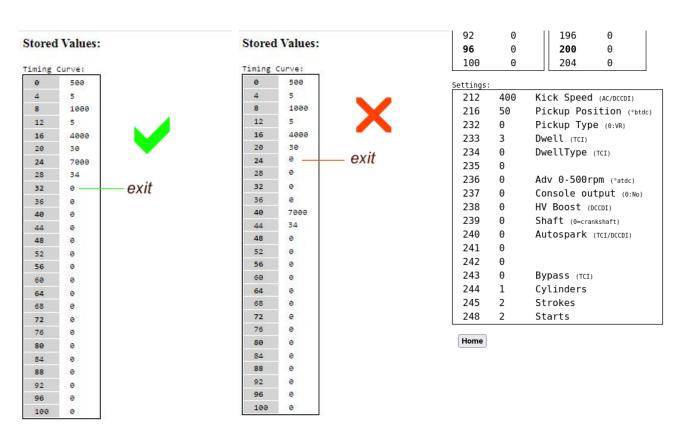


Curve N°2 is stored at addresses 104 to 204

Read

- To display the values that have been set, click on the **Read** button on the **Home** page :

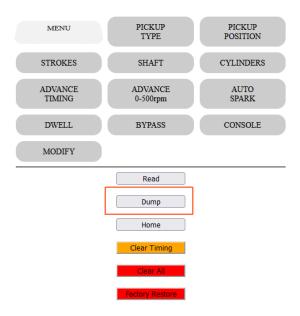




All values must be **consecutive** and in ascending order of RPM!

Dump

Read EEPROM addresses and display them in HEX values for <u>debug</u> purpose.

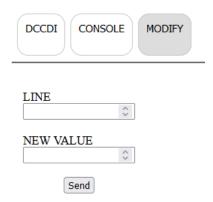


Dump EEPROM Hex Values:

0	F4	01	00	θ0	θ5	00	0θ	00
8	40	1F	00	Θ0	28	00	0θ	00
16	34	21	00	ΘΘ	28	00	ΘΘ	00
24	ΘΘ	00	00	ΘΘ	00	00	ΘΘ	00
32	ΘΘ	00	00	ΘΘ	00	00	ΘΘ	00
40	ΘΘ	00	00	ΘΘ	00	00	ΘΘ	00
48	ΘΘ	00	00	00	00	00	ΘΘ	00
56	ΘΘ	00	00	ΘΘ	00	00	ΘΘ	00
64	ΘΘ	00	00	ΘΘ	00	00	ΘΘ	00
72	00	00	00	00	00	00	ΘΘ	00
80	ΘΘ	00	00	ΘΘ	00	00	ΘΘ	00
88	00	00	00	00	00	00	ΘΘ	00
96	ΘΘ	00	00	ΘΘ	00	00	ΘΘ	00
104	ΘΘ	00	00	00	00	00	ΘΘ	00
112	ΘΘ	00	00	ΘΘ	00	00	ΘΘ	00
120	ΘΘ	00	00	ΘΘ	00	00	ΘΘ	00
128	ΘΘ	00	00	00	00	00	ΘΘ	00
136	FE	00	00	ΘΘ	00	00	ΘΘ	00
144	ΘΘ	00	00	ΘΘ	00	00	ΘΘ	00
152	ΘΘ	00	00	ΘΘ	00	00	ΘΘ	00
160	00	00	00	ΘΘ	00	00	ΘΘ	00
168	ΘΘ	00	00	ΘΘ	00	00	ΘΘ	00
176	00	00	00	ΘΘ	00	00	ΘΘ	00
184	ΘΘ	00	00	ΘΘ	00	00	ΘΘ	00
192	ΘΘ	00	00	ΘΘ	θΘ	00	ΘΘ	00
200	ΘΘ	00	00	θ0	00	00	ΘΘ	00
208	0Θ	00	00	ΘΘ	00	00	ΘΘ	00
216	32	00	00	Θ0	00	00	ΘΘ	00
224	02	00	00	ΘΘ	00	00	ΘΘ	00
232	00	00	00	Θ0	00	00	ΘΘ	00
240	00	00	00	θ0	θ1	00	ΘΘ	00

Home

Modification



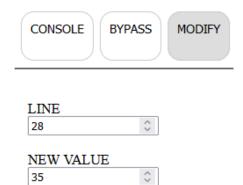
Say you want to modify the advance timing for 7000rpm and set 35° instead of 34°

In Read mode above, we saw that RPM 7000 is stored at address 24 and timing for 7000rpm is at address 28.



Since we want to modify the advance timing at line 28, we now have to enter:

Line 28
New value 35
then Send



Same thing to change any other values.

Remember: All timing values must be in <u>ascending</u> order of RPM and <u>no blank address</u> between timing values.

Use Read button to check that.

Send

Add points

Say you want to add one advance timing of 34° @ 8000rpm

In *Read* mode above, we saw that last RPM 7000 is stored at address 24 and timing for 7000rpm is at address 28.

The next 2 empty slots available are:

20	20		
24	7000		
28	34		
32	9		
36	0		
40	0		

Address 32 for RPM and Address 36 for timing

We now have to enter:

Line 32
New value 8000
then Send

Line 36
New value 34
then Send

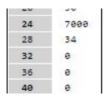
Remember: All timing values must be consecutive and in ascending order of RPM!

Use Read button to check that.

Clear points

Say you want to remove the last advance timing of 34° @ 7000rpm

In *Read* mode above, we saw that last RPM 7000 is stored at address 24 and timing for 7000rpm is at address 28.

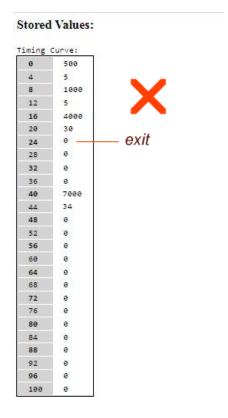


To zero out those values we now have to enter:

Line 24
New value 0
then Send

Line 28
New value 0
then Send

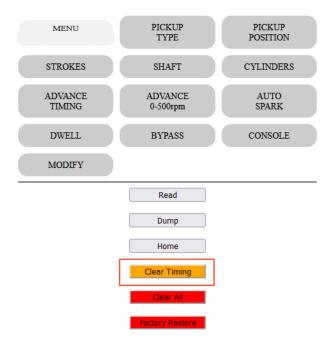
Remember: All timing values must be **consecutive** and in <u>ascending</u> order of RPM! Use Read button to check that.



Clear Timing

This button will clear TIMING values WITHOUT confirmation.

Pickup position, polarity, shaft, dwell etc are kept.



Browser shows:

Timing values cleared!

Please restart the ignition box.

This box now has no Advance Curve and cannot operate until you set timing values.

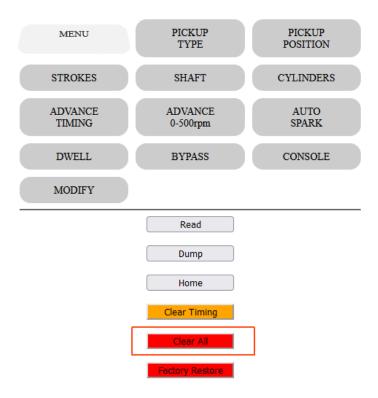
Restart the ignition box. (power off/power on)

Don't forget the Kill switch position if you want to return in Setup mode....

Clear All

This button will clear ALL values WITHOUT confirmation.

Timing, Pickup position, polarity, shaft, dwell etc are zeroed.



Browser shows:

EEPROM values cleared!

Please restart the ignition box.

This box is now empty and cannot operate until you set values. '

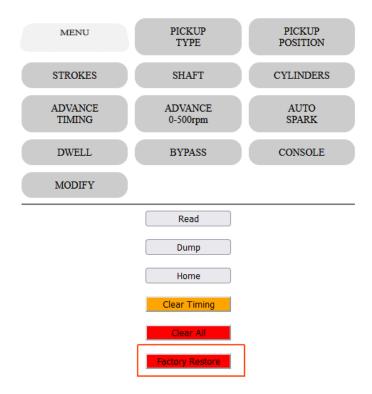
Restart the ignition box. (power off/power on)

Don't forget the Kill switch position if you want to return in Setup mode....

Factory Restore

This button will **Restore Factory Default** WITHOUT confirmation.

Timing, Pickup position, polarity, shaft, dwell etc are set to default values.



Browser shows:

Init All done!

This box now have a default Advance Curve which is not the one you need...

Tune the values before to start the engine!

Restart the ignition box. (power off/power on)

Don't forget the Kill switch position if you want to return in Setup mode....

Advanced settings

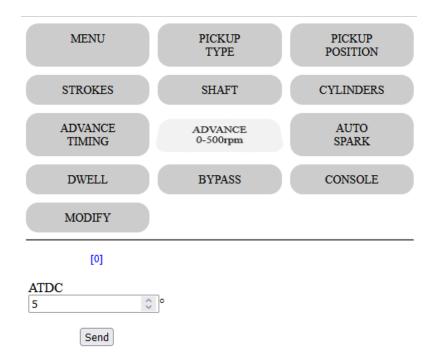
If you don't need those Extra settings, just let them to their default value.

Advance at kick start

Default: 0

Range of values: 0 to 10

For an easier Manual Kick start and to avoid kick backs, you can delay the advance between 0 to 500rpm to send the spark a few degrees **After** Top Dead Center (ATDC)



Current value appears in blue on the form.

Tech info:

If the measured period/rpm is less than 500rpm, the CPU uses the measured rpm (ie 320rpm) to determine when the next TDC will append during the next revolution, assuming the rpm remains constant.

If the engine speed decrease due to low inertia, the TDC calculation will be incorrect, resulting in an early spark.

To address this issue, the CPU adds an offset to the calculation, which equals the value of the "Advance 0-500" tab that the user may have set.

i.e., if the user specifies 20° ATDC, the CPU will calculate the theoretical next TDC and add 20° to the result.

If the measured rpm is over 500rpm, the CPU read the advance timing map the user has set to find which advance must be applied for this specific RPM (ie520rpm). No user offset will be used.

AutoSpark

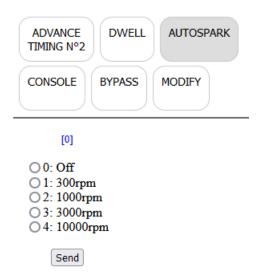
Default: Off

Range of values: 0ff, 300 1000, 3000, 10000rpm

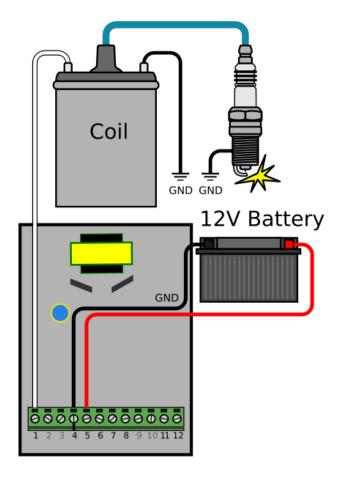
This autotest function is usable on TCI and DCCDI only.

The ignition box fires the ignition by itself at 300/1000/3000/10000rpm WITHOUT any pickup connected. This way you can test the wiring, the TCI/DCCDI, the ignition coil and sparkplug.

Of course, remove the sparkplug from the cylinder head and connect it's metal part to the bike frame.



Current value appears in blue on the form.

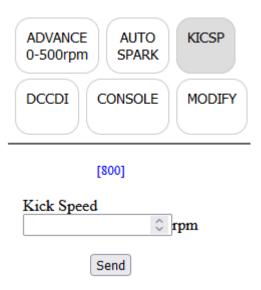


Kick Speed

Default: 800

Range of values: 100 to 1000rpm

For an easier Manual Kick start and to avoid kick backs, you can select what will be the RPM of the very first engine rotation when it is kick started.



Current value appears in blue on the form.

Tech info:

When a trigger signal comes (pickup or hall), the CPU measures the time between this pulse and the preceding one to determine the period, and hence the rpm.

At the very first pulse only, as there is no previous one, the period is unknown.

The CPU then uses the "kick speed" rpm (default 400rpm) or any other value the user may have specify.

The "kick speed" value will not be used for the following pulses because the period will be calculated based on two consecutive trigger pulses.

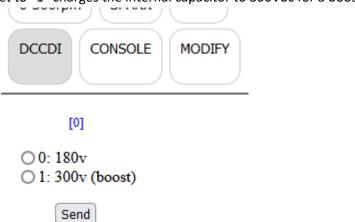
If there is more than 1sec between 2 pickup pulses, "kick speed" setting will be applied again for the next first pulse.

DC-CDI

Default: 0

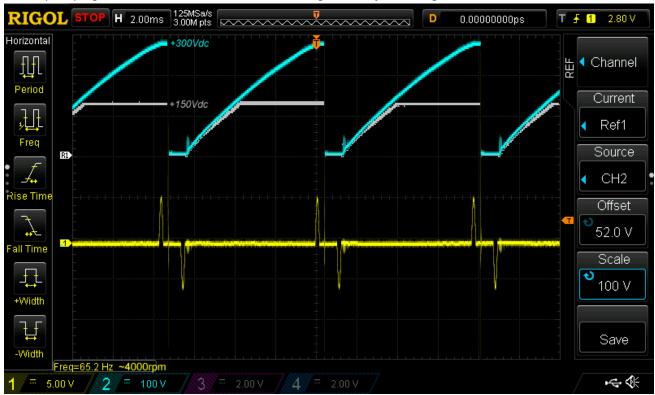
The DC converter output voltage is set to 180Vdc by default.

Set to "1" charges the internal capacitor to 300Vdc for a boost effect!



Current value appears in blue on the form.

Yellow: pickup signal blue boosted DC converter voltage, Pink default voltage.



(In Autospark mode, the voltage is always 300V)

Test Point

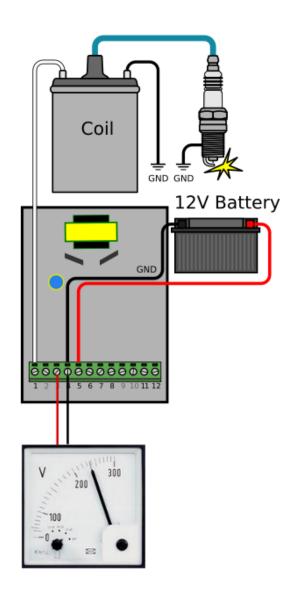
This DC-CDI ignition contains a DC converter ("a transformer") that transform a +12Vdc voltage into a 150Vdc or 300Vdc voltage.

This tension is available to measurement at pin 3. (/!\ Beware of Electric Shock)

To check the voltage:

- Turn off the DCCDI
- Connect a DC multimeter between ground pin 4 and TestPoint pin 3 in at least 350Vdc position.
- Turn on the DCCDI

DCCDI powered on, engine stopped	0Vdc
DCCDI powered on, engine running	150Vdc or 300Vdc depending on Settings
DCCDI powered on, Autospark mode 300rpm	300Vdc



Console

Default: Off

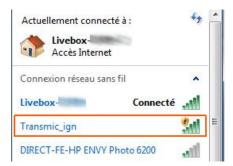
Enable the Console output:

- Turn the ignition box in **Setup Mode**
- Go to "CONSOLE", check "1" to enable the console output, press Send



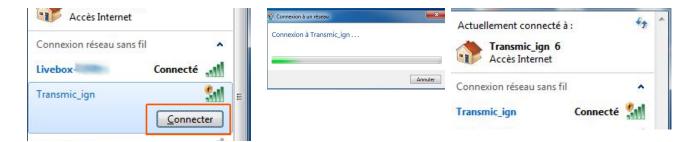
Current value appears in blue on the form.

- Power off the ignition box
- Disconnect the Kill wire from ground
- 1) Power on the ignition box, it goes in "Run Mode"
- 2) The **blue LED** flashes once if curve N°1 is selected or flashes twice for curve N°2
- 4) The ignition box also creates a WiFi AP (Access Point)
- 5) On your phone, laptop, PC, whatever, go to the **Wifi setting** and search for a new SSID called **Transmic_ign** You can see available SSID with a Wifi Analyzer as <u>NetSpot for Android</u> or <u>Wifi-Analyzer for W10</u>



6) Connect to it

From CDIv12r0 to CDIv12r2 *no password* was required Up from CDIv12r3 password is required: it's "*password*"



7) Start the engine

- 8) Once your device is connected to the AP, open up a **browser** and type in the address bar:
- Until version ACDCCDIv12r3c3: http://192.168.4.1
- From version ACDCCDIv12r4c0 (August2023) : http://192.168.4.1/console
- 9) After a few seconds, the browser should display both the **RPM and the advance timing** in degrees BTDC followed by 2 bargraphs

3360 39.29



Display appears ONLY when the engine is running.

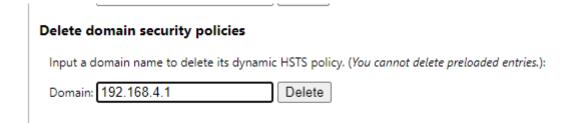
Because of the impact on Ignition box performance, please use it for debug only and disable this function when you are done with it!

Troubleshooting

Console URL is http:// NOT https:// but some browsers like Chrome automatically switch to https://

Workarounds

- Use Firefox. Close <u>all</u> Firefox windows than relaunch it.
- Use a lightweight, portable browser as **QtWeb**
- In Chrome, disable **HSTS** (HTTP Strict Transport Security) that forces to open websites in HTTPS:
 - Write **chrome://net-internals/#hsts** in the address bar.
 - Scroll down the page to :



- add 192.168.4.1 and hit Delete to disable Force https for this particular website.

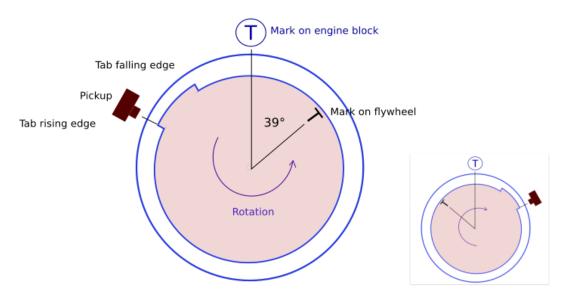
Running Mode

- 1) **Disconnect** the **Kill** wire from ground if you previously went into **Setup Mode**
- 2) Power on the ignition box, it goes in "Run Mode"
- 3) The **blue LED** flashes one time.
- 4) Start the engine. The blue LED **blinks** in sync **with RPM**.
- 5) When the engine runs, if **Kill** wire is connected **to ground** THEN it **stops** the engine.

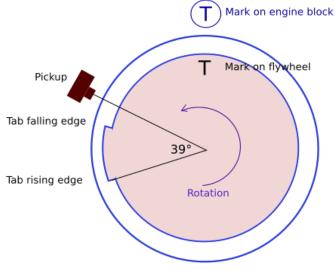
Case of Variable Reluctor aka VR pickup/pickup coil/trigger coil (For Hall sensor, read <u>Appendix2</u>)

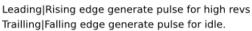
In the example below the pickup/sensor is set at 39° BTDC

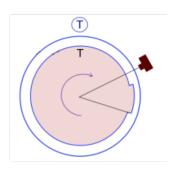
Method N°1 Pickup aligned with rising edge



Method N°2 Engine at TDC







 $calage TDC_pickup_2 methods.svg$

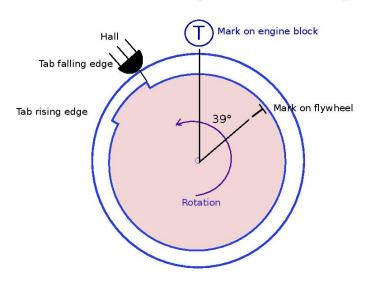
Case of Hall Effect Sensor

(For VR pickup/analog pickup read Appendix1)

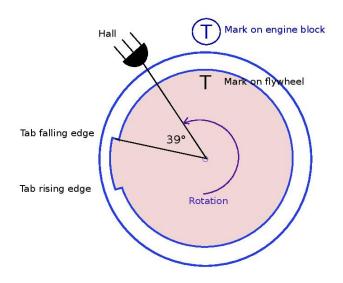
Find the physical position of the digital **Hall Sensor** relative to Top Dead Center.

In the example below the sensor is set at 39° BTDC

Method N°1 Hall sensor aligned with falling edge



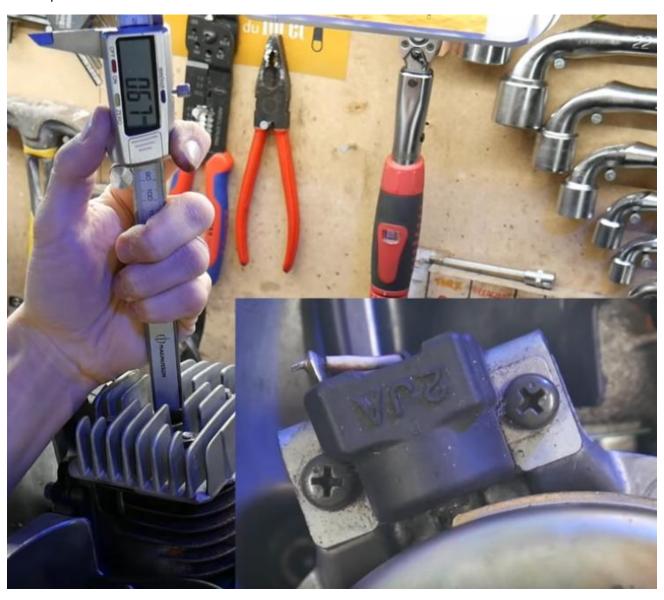
Method N°2
Engine at TDC



A) Remove the sparkplug, find the TDC position with a *dial indicator gauge* or a *caliper rule*:



B) Align the pickup with the beginning of the magnet on the rotor and measure the travel of the piston with the caliper rule:



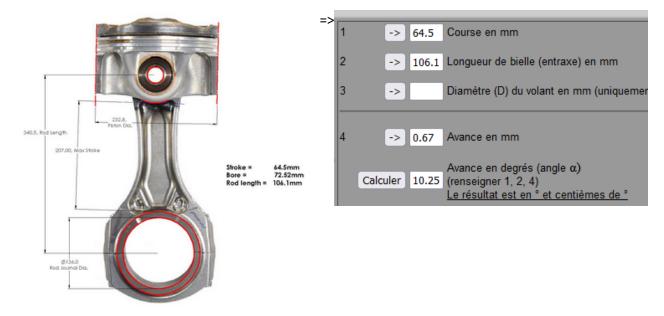
C) Use an online timing calculator to convert millimeters into degrees:

https://lambretta-images.com/tuningh/port-timing-calculators/degrees-to-mm-timing-calculator/

or

http://www.ajcshop.fr/Calculettes/html/calculette-convertisseur-allumage.htm

ie:



Tries and errors and Timing Lamp



If there is no mark on the flywheel, a possible way is as follows:

Method:

Remove the spark plug, insert a gauge in the sparkplug hole. Turn the flywheel until the piston is at TDC. Remove the gauge.

Draw 2 marks opposite each other on the flywheel and on the engine case. It's the TDC mark.

Print a *Timing Tape* from https://www.blocklayer.com/timing-tape
Align the 0 mark to the new TDC mark and stick the tape on the flywheel.

Set the ignition box with a pickup position of say 30° BTDC

Set the ignition box with a SAFE and FLAT timing curve at a static advance (ie : 10° BTDC from 500 to 4000rpm)

Put back the sparkplug and start the engine if possible

Otherwise plug the sparkplug in it's cap, tied the plug to the frame to have sparks, then rotate the engine with a drill machine (the faster the better).

With a timing lamp, take note where on the timing tape the spark appends.

Take note how much "off" is the timing.

Examples:

If the timing lamp shows 15° BTDC (instead of 10°) that mean the "*Pickup Position*" is off by 5° (15°-10°). The pickup position is the off by 5°. Increase the "*Pickup Position*" by 5. Real position is not 30° but 30° + 5° = 35°

Set the ignition box with a pickup position of 35° BTDC Using the timing lamp, check that the timing is now read at 10° Make small adjustment to the pkp position if necessary.

If the timing lamp shows 5° BTDC (instead of 10°) that mean the " $Pickup\ Position$ " is off by -5° (5°-10°). The pickup position is the off by -5°. Lower the " $Pickup\ Position$ " by 5. Real position is not 30° but 30° - 5° = 25°

Set the ignition box with a pickup position of 25° BTDC Using the timing lamp, check that the timing is now read at 10° Make small adjustment to the pkp position if necessary.

In one word:

If the Timing Lamp measure MORE advance than what is set in the user interface then INCREASE the "Pickup position"

If the Timing Lamp measure LESS advance than what is set in the user interface then LOWER the "Pickup position"