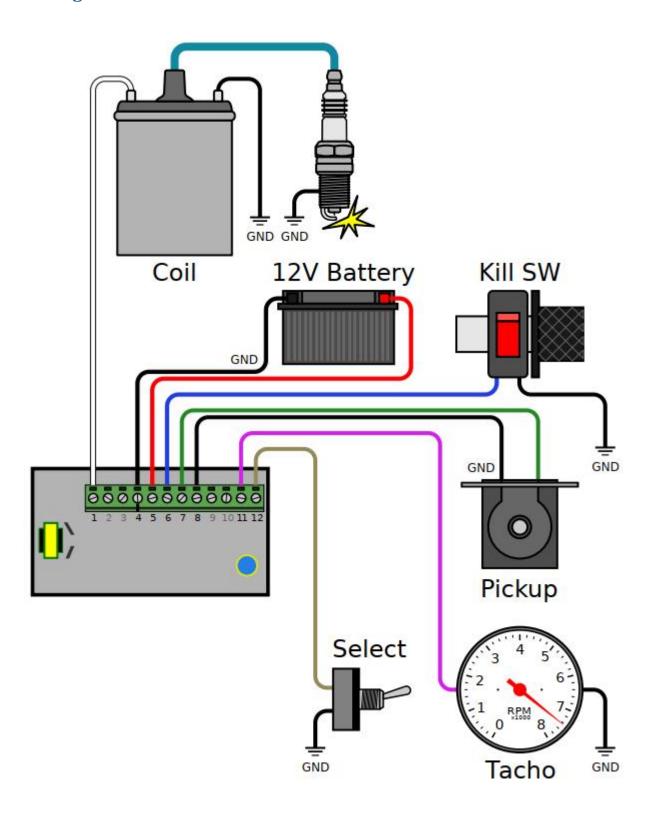
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Wiring



Connector



1	output	To ignition coil
2	output	not connected
3	input	not connected
4	input	Ground frame (=minus from battery)
5	input	+12Vdc from battery
6	input	Kill switch
7	input	Analog Pickup
8	input	Pickup or Hall Sensor Ground
9	input	Digital Hall Effect Sensor *
10	input	not connected

Tachometer *

12 input Curve Selection *

11 output

Kill Switch

The ignition uses the Kill switch input as a selector between <u>2 functions</u>:

- <u>Setup</u>
- Stop engine.

Setup Mode

- 1) Turn the Kill Switch ON (connector pin6 connected to ground) PRIOR to power on the ignition box.
- 2) Power on the ignition box with a 6 to 12v battery.

Warning: The Power and Ground connections MUST BE SECURE.

A power outage during the setup process may cause the ignition box to brick!

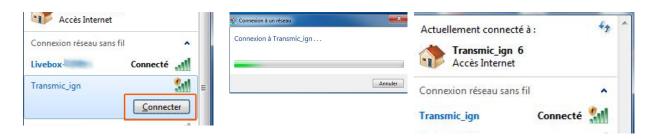
When the ignition box detects that the kill switch is already grounded, it turns into SETUP Mode.

- 3) The **Blue Led** <u>blinks 5 times</u> then flashes every <u>5 seconds</u>.
- 4) The ignition box starts a Wifi AP (Access Point)
- 5) On your phone, laptop, PC, whatever, go to the Wifi setting and search for a new SSID called Transmic_ign



6) Connect to it

From CDIv12r0 to CDIv12r2 *no password* was required Up from CDIv12r3 password is required: it's "*password*"



- 8) Once your device is connected to the AP, open up a browser and type in the address bar:
- Until version ACDCCDIv12r3c3:

http://192.168.4.1

- From version ACDCCDIv12r4c0 (August2023):

http://192.168.4.1/setup

(http not https!)

9) Once connected your browser should display:

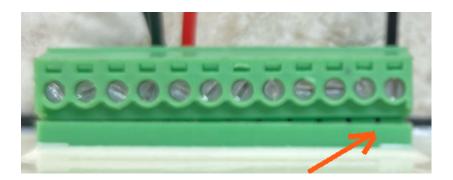
TRANSMIC.FR



10) Turn the Kill Switch OFF for Running mode.

No WiFi Access Point appears:

- Check that the 12pins connector is FULLY inserted and there is nothing preventing the male connector from fully engaging.



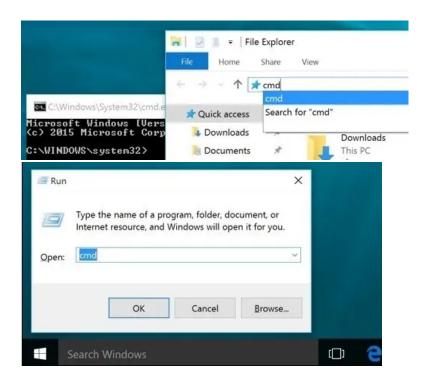
- You can see available SSID with a WiFi Analyzer as <u>NetSpot for Android</u> or <u>Wifi-Analyzer for W10</u>
- Reboot the ignition box. (Power off/power up)

WiFi Access Point appears:

- Connect to the WiFi AP and test the network connection from your laptop to the ignition box:

Open a command Prompt:

Type "cmd" into the address bar of File Explorer and hit Enter or Press Windows+R to open "Run" box. Type "cmd" and then click "OK"



ping the ignition box, it should replies:

C:\>ping 192.168.4.1

Pinging 192.168.4.1 with 32 bytes of data:

Reply from 192.168.1.1 : bytes=32 time<1ms TTL=64 **Reply** from 192.168.1.1 : bytes=32 time<1ms TTL=64 **Reply** from 192.168.1.1 : bytes=32 time<1ms TTL=64

Clear DNS cache

Windows: in MsDos console: C:\>ipconfig /flushdns

MacOS: in Terminal : sudo dscacheutil -flushcache

Linux: in Terminal: sudo systemd-resolve –flush-caches

Troubleshooting display

- Ignore any browser message saying it's not connected to internet:



It's a Warning, not an Error.

Indeed, it's connected ONLY to the Ignition box, not to the web. (It's impossible to reach Google and the ignition box at the same time)

Console URL is http:// NOT https:// but some browsers like Chrome automatically switch to secure https://

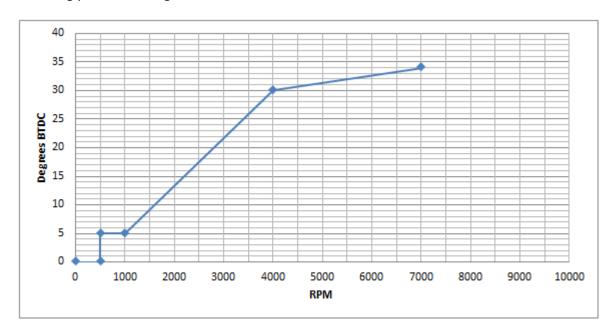
- in Chrome, disable **HSTS** (HTTP Strict Transport Security) that forces to open websites in HTTPS:
 - Write chrome://net-internals/#hsts in the address bar.
 - Scroll down the page to:

Delete domain security policies Input a domain name to delete its dynamic HSTS policy. (You cannot delete preloaded entries.): Domain: 192.168.4.1

- add 192.168.4.1 and hit Delete to disable Force https for this particular website.
- Or use Firefox. Close all Firefox windows than relaunch it.
- Or use a lightweight, portable browser as **QtWeb**

Ignition Timing

Assuming you want this ignition curve:



One can define the curve with 4 points but you can use up to 13 points.

(0 to 500rpm at 0° BTDC is <u>hard coded</u> for no kickback.)

The curve above is defined by 4 pairs of values

```
500 rpm = 5° BTDC

1000 rpm = 5° BTDC

4000 rpm = 30° BTDC

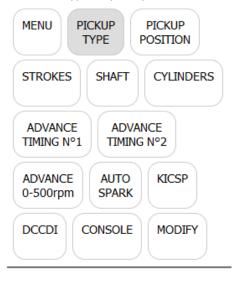
7000 rpm = 34° BTDC
```

Those 4 couples of values MUST be filled out in the form <u>consecutively and in ascending order</u> of RPM along with the pickup position.

Pickup Type

Default: 0

Select the type of pickup attached to the CDI.



[0]

- 0: Analog Pickup Coil (VR)
- 1: Digital Hall Effect Sensor *

Send

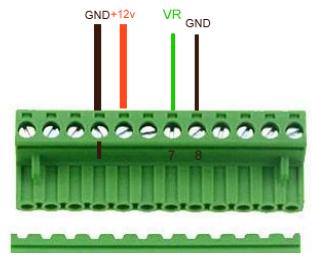
* option

0 = VR stands for Variable Reluctor aka pickup coil (Analog signal)

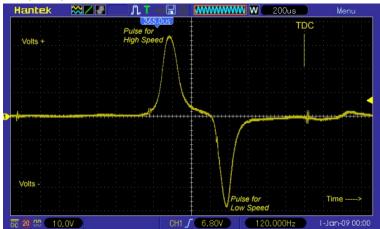
1 = Hall Effect Sensor (Digital signal) *

VR pickup

Analog VR pickup is connected between pin 7 and pin 8/gnd



The pickup coil MUST be connected in order to send a **POSITIVE PULSE FIRST**.



If the first pulse is Negative then the timing will be completely off (spark AFTER TDC) so no damage except hot engine.

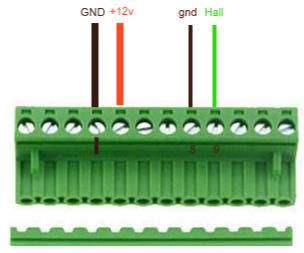
Just swap the wires to change the polarity!

To avoid ElectroMagnetic Interference (EMI) it's safer to connect the pickup sensor through a shielded cable. Shield grounded on one side only.

Twisted pair is better.

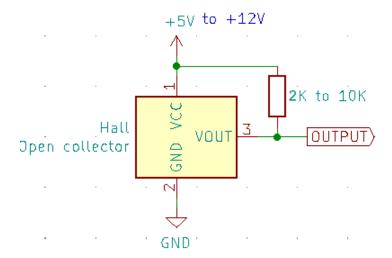
Hall Sensor

Digital Hall Sensor is connected between pin 9 and pin 8/gnd

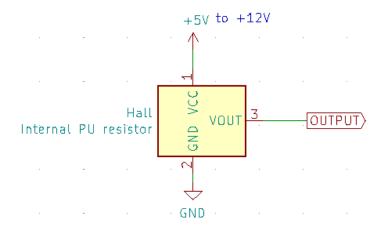


2 types of Sensors

- Hall sensors with **open-collector** output, give a floating voltage when no magnet. They needs a pull-up resistor.



- Hall sensors with **built-in pull-up resistor** give positives voltage when no magnet.

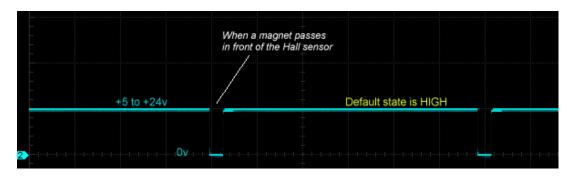


Hall sensors require a +5v to +12vdc supply voltage. See datasheet

You can even connect an **Optical Sensor** as long as it puts out a CLEAN square signal similar to the one above.

See Appendix 2 for Position

Output of a Hall sensor



Timing

The ignition box uses the **rising edge** of the Hall sensor signal.



Pickup Position

Default: 50

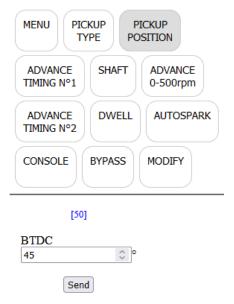
Range of values: 1 to 180

- Go back to the opened browser and first thing first, enter the **Pickup Position** then click **Send** Formula is: **Pickup position** = **Base advance** + **Magnet Length**

Magnet Length:



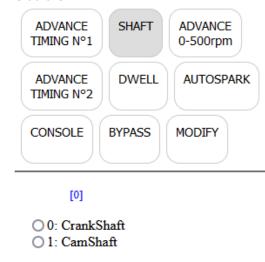
See <u>Appendix</u> 1,2,3,4 to find the physical position of the pickup relative to TDC.



- The **blue Led flashes** when values are processed.

Shaft

Default: 0



Current value appears in blue on the form.

Send

- Select if the pickup is placed on the crankshaft through the flywheel (2stk,4stk) with 1 pulse per rotation or is on the camshaft (4stk) with 1 pulse per 2 rotations.

Advance Timing

- Proceed now to enter the advance timing.

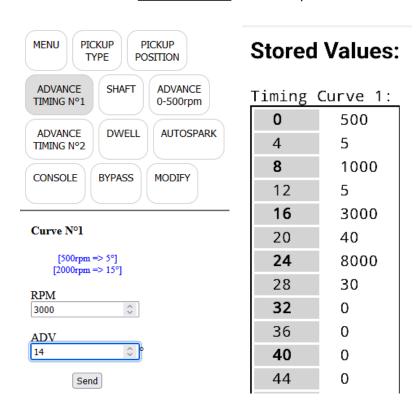
We want to setup:

```
500 \text{ rpm} = 5^{\circ} \text{ BTDC}
1000 \text{ rpm} = 5^{\circ} \text{ BTDC}
4000 \text{ rpm} = 30^{\circ} \text{ BTDC}
7000 \text{ rpm} = 34^{\circ} \text{ BTDC}
```

Enter values consecutively in ascending order of RPM!

Pair 500:5 first etc etc...

7000 being the <u>last value</u> (as the firmware stops reading when it meets a null value), 7000 will act as the <u>hard rev-limiter</u>: No more sparks at 7001 RPM!



RPM can be entered with a 100rpm step but RPM will be measured with **1rpm** precision.

Timing can be entered with a precision of 1° but the processor calculate all timing values between the points you entered, using linear interpolation so an **accuracy of 0.1°** is done at this step.

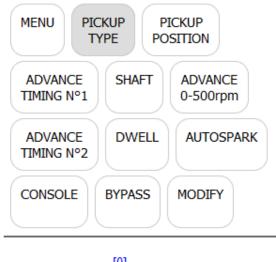
Any timing values will be COMPLETELY OFF IF PICKUP POSITION IS FALSE: **PICKUP POSITION IS KEY**

See <u>Appendix 1</u> for Position

Curve N°1 is stored at addresses 0 to 100

Pickup Polarity

Default: 0



[0]

- 0: Analog Pickup Coil (VR)
- 1: Digital Hall Effect Sensor *

Send

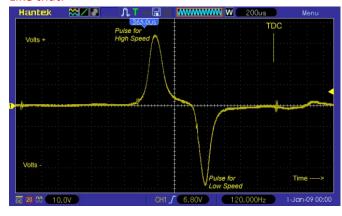
* option

Current value appears in blue on the form.

When the LEADING edge of the magnet passes in front of the pickup coil, a wave is produced and another wave of opposite voltage is generated when the FALLING edge of the magnet leaves the pickup coil. Depending on the wiring, the first pulse at Leading Edge can be positive (then negative at Falling edge), or the exact opposite.

Pickup Polarity MUST be Positive then Negative to work with this CDI

Like that:



Select curve

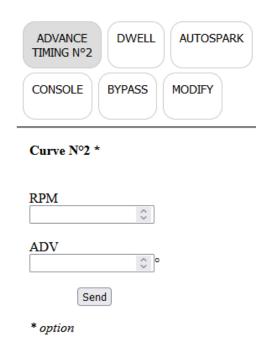
Default: curve N°1

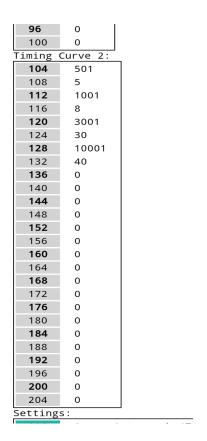
If you bought the 2 curves option, then connect a switch between connector pin 12 and ground.

When switch is **open** (or no switch connected), **curve N°1** is used.

If switch is **on** (pin 12 connected to ground) <u>BEFORE</u> turning on the ignition box, then **curve N°2** will be used.

You cannot change the curve while running. (The switch is not read by the ignition)

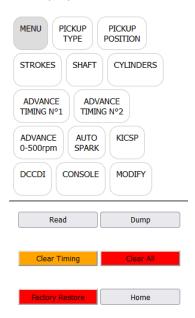


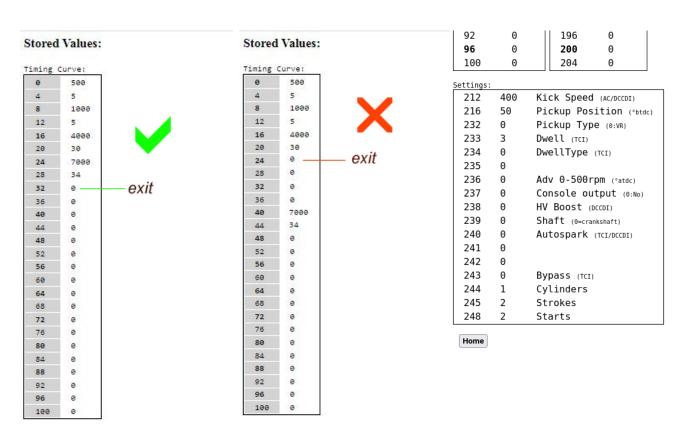


Curve N°2 is stored at addresses 104 to 204

Read

- To display the values that have been set, click on the **Read** button on the **Home** page :





All values must be consecutive and in ascending order of RPM!

Dump

Read EEPROM addresses and display them in HEX values for <u>debug</u> purpose.

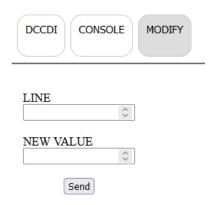


Dump EEPROM Hex Values:

0 F4 01 00 00 05 00 00 00 8 40 1F 00 00 28 00 00 00 16 34 21 00 00 28 00 00 00 24 00									
16 34 21 00 00 28 00 00 00 24 00 00 00 00 00 00	0	F4	01	00	θ0	θ5	00	00	00
24 00<	8	4θ	1F	00	ΘΘ	28	00	ΘΘ	00
32 00 00 00 00 00 00 00 00 00	16	34	21	00	ΘΘ	28	00	ΘΘ	00
40 00 00 00 00 00 00 00 00 00 00 48 00 00 00 00 00 00 00 00 00 00 00 00 00	24	0θ	00	00	00	00	00	ΘΘ	00
48 00 00 00 00 00 00 00 00 00	32	0θ	00	00	ΘΘ	00	00	ΘΘ	00
56 00 00 00 00 00 00 00 00 00	40	0θ	00	00	ΘΘ	00	00	ΘΘ	00
64 00 00 00 00 00 00 00 00 00 00 72 00 00 00 00 00 00 00 00 00 00 00 00 00	48	0θ	00	00	ΘΘ	00	00	ΘΘ	00
72 00 00 00 00 00 00 00 00 00	56	0θ	00	00	ΘΘ	00	00	ΘΘ	00
80 00 00 00 00 00 00 00 00 00 00 88 00 00	64	0θ	00	00	ΘΘ	00	00	ΘΘ	00
88	72	0θ	00	00	ΘΘ	00	00	ΘΘ	00
96 00 00 00 00 00 00 00 00 00 00 112 00 00 00 00 00 00 00 00 00 00 00 00 00	80	ΘΘ	00	00	ΘΘ	00	00	ΘΘ	00
104 00 00 00 00 00 00 00 00 00 112 00 00 00 00 00 00 00 00 00 00 00 00 128 00 00 00 00 00 00 00 00 00 00 136 FE 00 00 00 00 00 00 00 00 00 00 00 00 00	88	0θ	00	00	ΘΘ	00	00	ΘΘ	00
112 00 00 00 00 00 00 00 00 00 00 128 00 00 00 00 00 00 00 00 00 00 00 00 136 FE 00 00 00 00 00 00 00 00 00 144 00 00 00 00 00 00 00 00 00 00 00 00 0	96	0θ	00	00	ΘΘ	00	00	ΘΘ	00
120 00 00 00 00 00 00 00 00 00 00 128 00 00 00 00 00 00 00 00 00 00 00 00 136 FE 00 00 00 00 00 00 00 00 00 144 00 00 00 00 00 00 00 00 00 00 00 00 0	104	ΘΘ	00	00	ΘΘ	00	00	ΘΘ	00
128 00 00 00 00 00 00 00 00 00 00 136 FE 00 00 00 00 00 00 00 00 00 144 00 00 00 00 00 00 00 00 00 152 00 00 00 00 00 00 00 00 00 00 00 00 00	112	0θ	00	00	ΘΘ	00	00	ΘΘ	00
136 FE 00	120	ΘΘ	00	00	ΘΘ	00	00	ΘΘ	00
144 00	128	ΘΘ	00	00	ΘΘ	00	00	ΘΘ	00
152 00 00 00 00 00 00 00 00 00 00 168 00 00 00 00 00 00 00 00 00 00 00 00 00	136	FE	00	00	ΘΘ	00	00	ΘΘ	00
160 00 00 00 00 00 00 00 00 00 00 168 00 00 00 00 00 00 00 00 00 00 00 00 00	144	ΘΘ	00	00	ΘΘ	00	00	ΘΘ	00
168 00	152	ΘΘ	00	00	00	00	00	ΘΘ	00
176 00 00 00 00 00 00 00 00 00 00 184 00 00 00 00 00 00 00 00 00 00 00 00 00	160	0θ	00	00	ΘΘ	00	00	ΘΘ	00
184 00 00 00 00 00 00 00 00 00 00 192 00 00 00 00 00 00 00 00 00 00 00 00 00	168	ΘΘ	00	00	ΘΘ	00	00	ΘΘ	00
192 00 00 00 00 00 00 00 00 00 00 00 00 00	176	0θ	00	00	ΘΘ	00	00	ΘΘ	00
200 00 00 00 00 00 00 00 00 00 00 216 32 00 00 00 00 00 00 00 00 00 224 02 00 00 00 00 00 00 00 00 232 00 00 00 00 00 00 00 00 00 00 00 00 00	184	ΘΘ	00	00	ΘΘ	00	00	ΘΘ	00
208 00 00 00 00 00 00 00 00 00 00 216 32 00 00 00 00 00 00 00 00 00 00 00 00 00	192	ΘΘ	00	00	00	00	00	ΘΘ	00
216 32 00 00 00 00 00 00 00 00 224 02 00 00 00 00 00 00 00 00 00 00 00 00	200	0θ	00	00	ΘΘ	00	00	ΘΘ	00
224 02 00 00 00 00 00 00 00 232 00 00 00 00 00 00 00 00									
232 00 00 00 00 00 00 00 00	216	32	00	00	Θ0	00	00	ΘΘ	00
	224	02	00	00	Θ0	00	00	ΘΘ	00
240 00 00 00 00 01 00 00 00							00		
	240	00	00	00	00	θ1	00	00	00

Home

Modification



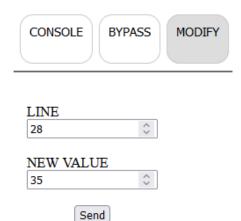
Say you want to modify the advance timing for 7000rpm and set 35° instead of 34°

In *Read* mode above, we saw that RPM 7000 is stored at address 24 and timing for 7000rpm is at address 28.



Since we want to modify the advance timing at line 28, we now have to enter:

Line 28
New value 35
then Send



Same thing to change any other values.

Remember: All timing values must be in <u>ascending</u> order of RPM and <u>no blank address</u> between timing values.

Use <u>Read</u> button to check that.

Add points

Say you want to add one advance timing of 34° @ 8000rpm

In *Read* mode above, we saw that last RPM 7000 is stored at address 24 and timing for 7000rpm is at address 28.

The next 2 empty slots available are:

20	30
24	7000
28	34
32	9
36	0
40	0

Address 32 for RPM and Address 36 for timing

We now have to enter:

Line 32
New value 8000
then Send

Line 36
New value 34
then Send

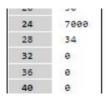
Remember: All timing values must be consecutive and in ascending order of RPM!

Use <u>Read</u> button to check that.

Clear points

Say you want to remove the last advance timing of 34° @ 7000rpm

In *Read* mode above, we saw that last RPM 7000 is stored at address 24 and timing for 7000rpm is at address 28.



To zero out those values we now have to enter:

Line 24
New value 0
then Send

Line 28
New value 0
then Send

Remember: All timing values must be **consecutive** and in <u>ascending</u> order of RPM! Use <u>Read</u> button to check that.

Stored Values: Timing Curve: exit 0 -

Clear Timing

This button will clear TIMING values WITHOUT confirmation.

Pickup position, polarity, shaft, dwell etc are kept.



Browser shows:

Timing values cleared!

Please restart the ignition box.

This box now has no Advance Curve and cannot operate until you set timing values.

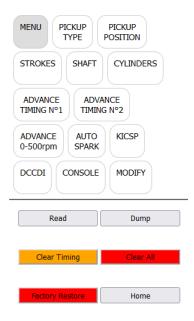
Restart the ignition box. (power off/power on)

Don't forget the Kill switch position if you want to return in Setup mode....

Clear All

This button will clear ALL values WITHOUT confirmation.

Timing, Pickup position, polarity, shaft, dwell etc are zeroed.



Browser shows:

EEPROM values cleared!

Please restart the ignition box.

This box is now empty and cannot operate until you set values. '

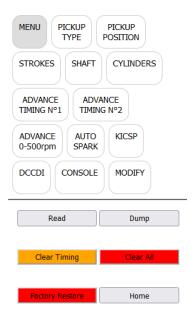
Restart the ignition box. (power off/power on)

Don't forget the Kill switch position if you want to return in Setup mode....

Factory Restore

This button will **Restore Factory Default** WITHOUT confirmation.

Timing, Pickup position, polarity, shaft, dwell etc are set to default values.



Browser shows:

Init All done!

This box now have a default Advance Curve which is not the one you need...

Tune the values before to start the engine!

Restart the ignition box. (power off/power on)

Don't forget the Kill switch position if you want to return in Setup mode....

Advanced settings

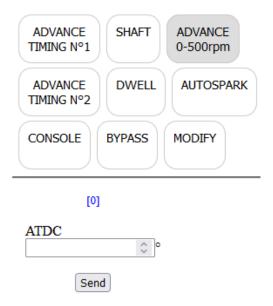
If you don't need those Extra settings, just let them to their default value.

Advance at kick start

Default: 0

Range of values: 0 to 10

For an easier Manual Kick start and to avoid kick backs, you can delay the advance between 0 to 500rpm to send the spark a few degrees **After** Top Dead Center (ATDC)



AutoSpark

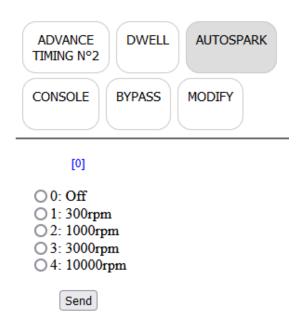
Default: Off

Range of values: 0ff, 300 1000, 3000, 10000rpm

This autotest function is usable on TCI and DCCDI only.

The ignition box fires the ignition by itself at 300/1000/3000/10000rpm WITHOUT any pickup connected. This way you can test the wiring, the TCI/DCCDI, the ignition coil and sparkplug.

Of course, remove the sparkplug from the cylinder head and connect it's metal part to the bike frame.

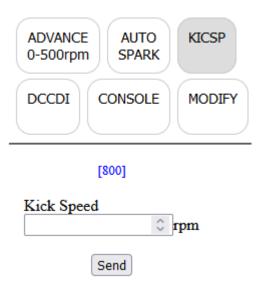


Kick Speed

Default: 800

Range of values: 100 to 1000rpm

For an easier Manual Kick start and to avoid kick backs, you can select what will be the RPM of the very first engine rotation when it is kick started.

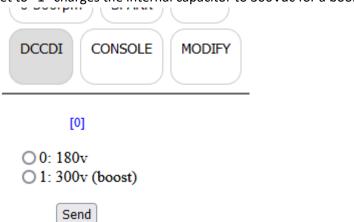


DC-CDI

Default: 0

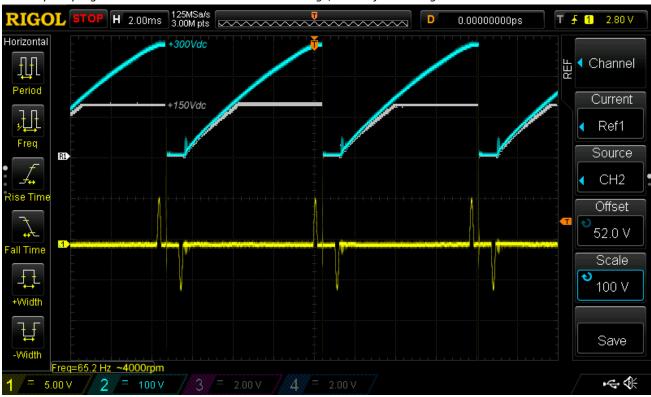
The DC converter output voltage is set to 180Vdc by default.

Set to "1" charges the internal capacitor to 300Vdc for a boost effect!



Current value appears in blue on the form.

Yellow: pickup signal blue boosted DC converter voltage, Pink default voltage.



Console

Default: Off

Enable the Console output:

- Turn the ignition box in **Setup Mode**
- Go to "CONSOLE", check "1" to enable the console output, press Send

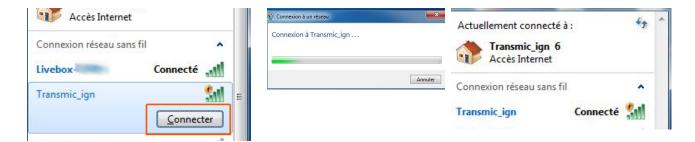


- Power off the ignition box
- Disconnect the Kill wire from ground
- 1) Power on the ignition box, it goes in "Run Mode"
- 2) The **blue LED** flashes once if curve N°1 is selected or flashes twice for curve N°2
- 4) The ignition box also creates a WiFi AP (Access Point)
- 5) On your phone, laptop, PC, whatever, go to the **Wifi setting** and search for a new SSID called **Transmic_ign** You can see available SSID with a Wifi Analyzer as <u>NetSpot for Android</u> or <u>Wifi-Analyzer for W10</u>



6) Connect to it

From CDIv12r0 to CDIv12r2 *no password* was required Up from CDIv12r3 password is required: it's "*password*"



7) Start the engine

- 8) Once your device is connected to the AP, open up a **browser** and type in the address bar:
- Until version ACDCCDIv12r3c3: http://192.168.4.1
- From version ACDCCDIv12r4c0 (August2023) : http://192.168.4.1/console
- 9) After a few seconds, the browser should display both the **RPM and the advance timing** in degrees BTDC followed by 2 bargraphs

3360 39.29



Display appears ONLY when the engine is running.

Troubleshooting

Console URL is http:// NOT https:// but some browsers like Chrome automatically switch to https://

Workarounds

- Use Firefox. Close <u>all</u> Firefox windows than relaunch it.
- Use a lightweight, portable browser as **QtWeb**
- In Chrome, disable **HSTS** (HTTP Strict Transport Security) that forces to open websites in HTTPS:
 - Write **chrome://net-internals/#hsts** in the address bar.
 - Scroll down the page to :

Delete domain security policies
Input a domain name to delete its dynamic HSTS policy. (You cannot delete preloaded entries.):
Domain: 192.168.4.1 Delete

- add 192.168.4.1 and hit Delete to disable Force https for this particular website.

Running Mode

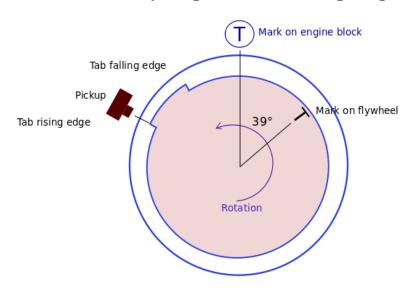
- 1) **Disconnect** the **Kill** wire from ground if you previously went into **Setup Mode**
- 2) Power on the ignition box, it goes in "Run Mode"
- 3) The **blue LED** flashes one time.
- 4) Start the engine. The blue LED blinks in sync with RPM.
- 5) When the engine runs, if **Kill** wire is connected **to ground** THEN it **stops** the engine.

/!\ XT550-XT600: Kill the engine with the Kill switch BEFORE shutting down the +12v. (As it's a software kill, the processor must be powered on to be able to kill the engine!)

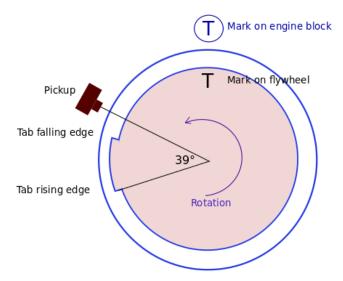
Find the Hall sensor or Pickup position.

In the example below the pickup/sensor is set at 39° BTDC

Method N°1 Pickup aligned with rising edge



Method N°2 Engine at TDC

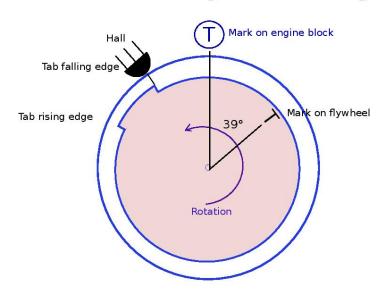


Leading|Rising edge generate pulse for high revs Trailling|Falling edge generate pulse for idle.

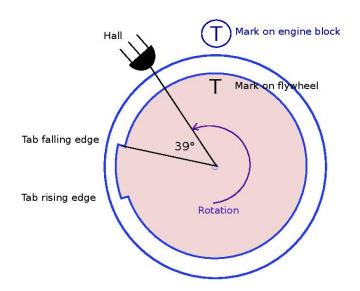
Find the physical position of the digital **Hall Sensor** relative to Top Dead Center.

In the example below the sensor is set at 39° BTDC

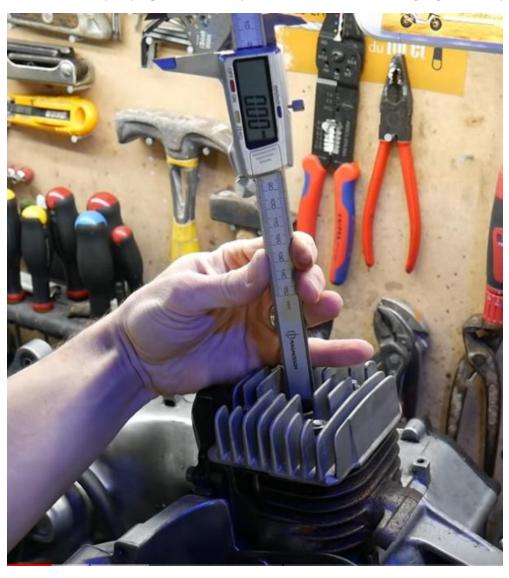
Method N°1 Hall sensor aligned with falling edge



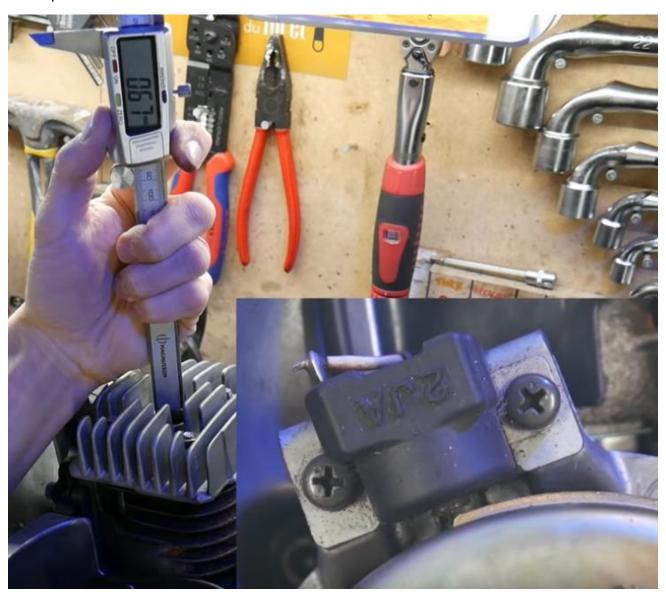
Method N°2
Engine at TDC



A) Remove the sparkplug, find the TDC position with a *dial indicator gauge* or a *caliper rule*:



B) Align the pickup with the beginning of the magnet on the rotor and measure the travel of the piston with the caliper rule:



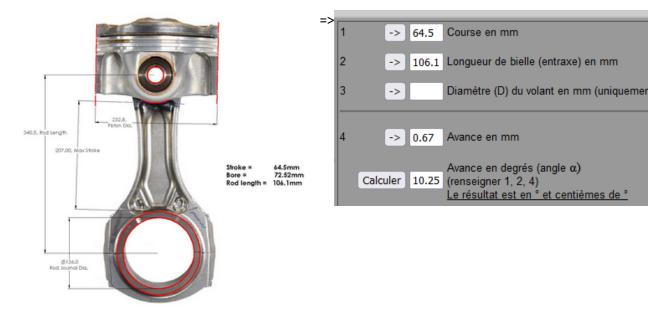
C) Use an online timing calculator to convert millimeters into degrees:

 $\underline{https://lambretta-images.com/tuningh/port-timing-calculators/degrees-to-mm-timing-calculator/}$

or

http://www.ajcshop.fr/Calculettes/html/calculette-convertisseur-allumage.htm

ie:



Tries and errors and Timing Lamp



First method:

For example, if you set the "*Pickup position*" to 40° BTDC plus some timing points then with your Timing Lamp you measure MORE advance than what is set in the user interface (ie you measure 35° instead of 30°@3000rpm) then INCREASE the "*Pickup position*" $(40^{\circ} \rightarrow 45^{\circ})$

If you set the "Pickup position" to 40° BTDC and with your Timing Lamp you measure LESS advance than what is set in the user interface (ie you measure 25 instead of 30°@3000rpm) then LOWER the "Pickup position" $(40^{\circ} \rightarrow 35^{\circ})$

Second method:

Set a FLAT advance timing with a SAFE value:

Example: 10° BTDC from 500 to 4000rpm

Run the bike and measure the timing with a Timing Lamp.

If you measure say 15° BTDC (instead of 10°) that mean the "*Pickup Position*" is off by 5°. Increase the "*Pickup Position*" by 5.

If you measure say 5° BTDC (instead of 10°) that mean the "*Pickup Position*" is off by 5°. Lower the "*Pickup Position*" by 5.